

# IE 361 Module 30

## Control Charts for Counts (Attributes Data) Part 2

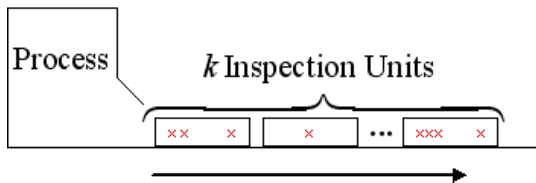
Reading: Section 3.3 *Statistical Methods for Quality Assurance*

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# Control Charts for Mean Nonconformities per Unit

The scenario under which a  $u$  chart or ( $c$  chart) is potentially appropriate is one where periodically  $k$  inspection units of product or production from a process are looked at and

$X$  = the total number of "nonconformities" found across those  $k$  units is observed. This is illustrated in the following figure, where "x"'s represent nonconformities.



**Figure:** Cartoon of  $k$  Inspection Units of Process Output and  $X$  "Nonconformities"

# Control Charts for Mean Nonconformities per Unit

In this kind of circumstance, the notation

$$\hat{u} = \frac{X}{k} = \text{the sample rate of nonconformities per unit}$$

is standard, and

- control charts for  $\hat{u}$  are called ***u* charts**
- control charts for the special case where  $k = 1$  and thus  $\hat{u} = X$  are called ***c* charts**

# Probability Basis for Control Limits

If the process producing items/outcomes is physically stable and produces nonconformities **at a rate of  $\lambda$  per unit**, a reasonable probability model for  $X$  (met in Stat 231) is the

Poisson ( $k\lambda$ )

distribution (the Poisson distribution with mean  $\mu_X = k\lambda$ ).

A Stat 231 fact about the Poisson distribution is that its mean and variance are the same, that is that

$$\sigma_X = \sqrt{\mu_X}$$

So in the present context

$$\mu_X = k\lambda \quad \text{and} \quad \sigma_X = \sqrt{k\lambda}$$

and in turn that

$$\mu_{\hat{u}} = \lambda \quad \text{and} \quad \sigma_{\hat{u}} = \sqrt{\frac{\lambda}{k}}$$

# Standards Given Control Limits

These probability facts lead to **standards given ( $u$  chart) control limits for  $\hat{u}$**

$$LCL_{\hat{u}} = \lambda - 3\sqrt{\frac{\lambda}{k}} \quad \text{and} \quad UCL_{\hat{u}} = \lambda + 3\sqrt{\frac{\lambda}{k}}$$

and for the case of  $k = 1$  (so that  $\hat{u} = X$ ) **standards given ( $c$  chart) control limits for  $X$**

$$LCL_X = \lambda - 3\sqrt{\lambda} \quad \text{and} \quad UCL_X = \lambda + 3\sqrt{\lambda}$$

# u Chart Example

## Example 30-1

Below are some artificially generated (using  $\lambda = 2.0$ ) Poisson data,  $X$ . We may consider these to be either counts or rates for a constant ( $k = 1$ ) number of inspection units.

Sample	1	2	3	4	5	6	7	8	9	10
$X$	2	2	1	2	2	3	4	3	2	0
Sample	11	12	13	14	15	16	17	18	19	20
$X$	2	0	3	2	1	5	2	2	1	3

Standards given control limits for  $X$  would then be

$$CL_X = 2 \quad \text{and} \quad UCL_X = \lambda + 3\sqrt{\lambda} = 2 + 3\sqrt{2} = 6.24$$

and no lower control limit would be used since  $2 - 3\sqrt{2}$  is negative. Clearly, none of the values  $X$  in the table would plot above the upper control limit and there is no indication of "lack of control"/deviation from the  $\lambda = 2.0$  nonconformities per unit picture of process performance under which the above limits are developed.

# u Chart Example

## Example 30-1 continued (Varying Amounts of Inspection)

To extend this example a bit, suppose that an additional 5 inspection Periods are involved, but now the number of inspection units observed per period is no longer constant (at " $k = 1$ "), and in fact that the table below is relevant.

Sample	$k$	$X$	$\hat{u} = \frac{X}{k}$	$UCL_{\hat{u}} = 2 + 3\sqrt{\frac{2}{k}}$	$LCL_{\hat{u}}$
21	1.5	2	1.33	5.67	none
22	1	1	1.00	6.24	none
23	.75	2	2.67	6.90	none
24	.5	1	2.00	8.00	none
25	3	5	1.67	5.29	none

# u Chart Example

## Example 30-1 continued (Shewhart u Chart)

The following figure is a JMP control chart for the whole data set, and there is no reason in these data to doubt that the nonconformity rate is constant at  $\lambda = 2.0$  per inspection unit. (Note that JMP in ambiguous fashion indicates that  $LCL = 0$ . It is better practice and provides clearer intent to say that there is **no lower control limit**.)

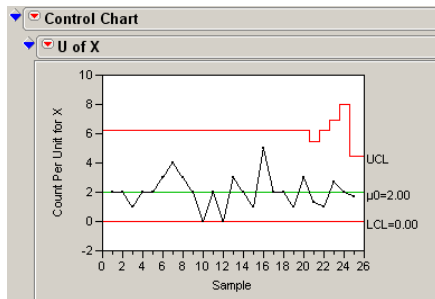


Figure: Standards Given ( $\lambda = 2.0$ )  $u$  Chart for the Artificial Data

## Retrospective Control Limits

Retrospective control limits for  $\hat{u}$  are obtained (as always) by making a provisional assumption of process stability and estimating process parameters (here, the value  $\lambda$ ). The most sensible estimate obtainable from  $r$  values  $X_i$  based on respective numbers of inspection units  $k_i$  is

$$\begin{aligned}\hat{\lambda}_{\text{pooled}} &= \frac{\text{total nonconformities observed}}{\text{total inspection units}} \\ &= \frac{X_1 + X_2 + \cdots + X_r}{k_1 + k_2 + \cdots + k_r}\end{aligned}$$

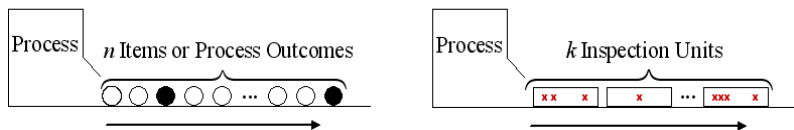
**Example 30-1 continued** There are a total of 53 nonconforming outcomes indicated among the 26.75 inspection units. So

$$\hat{\lambda}_{\text{pooled}} = \frac{53}{26.75} = 1.98$$

and there is negligible difference between the standards given chart on panel 8 and the retrospective control chart that would be made using this.

# $p$ versus $u$ Charts

Students sometimes have a difficult time identifying whether a given application calls for a  $p$  chart or for a  $u$  chart. Both  $\hat{p}$  and  $\hat{u}$  are kinds of "rates," but they are intrinsically different. For one thing, it is perfectly possible for  $\hat{u}$  to exceed 1.0, while  $\hat{p}$  is always between 0 and 1. The figure below lays the two basic scenarios side by side.



**Figure:** Comparison of "Fraction Nonconforming" and "Mean Nonconformities per Unit" Scenarios

In the  $p$  chart/"fraction nonconforming" context,  $n$  discrete items or outcomes are individually each either acceptable or nonconforming, and  $\hat{p}$  is the sample fraction nonconforming. In the  $u$  chart/"mean nonconformities per unit" context,  $k$  inspection units of process output potentially suffer nonconformities, and  $\hat{u}$  is the sample rate at which these are observed per unit.

It is worth saying again that the table in Section 3.7 of *SMQA* summarizes the control limit formulas for both the "attributes data" of this and the previous module and for the "measurements data" of Modules 26 and 27.